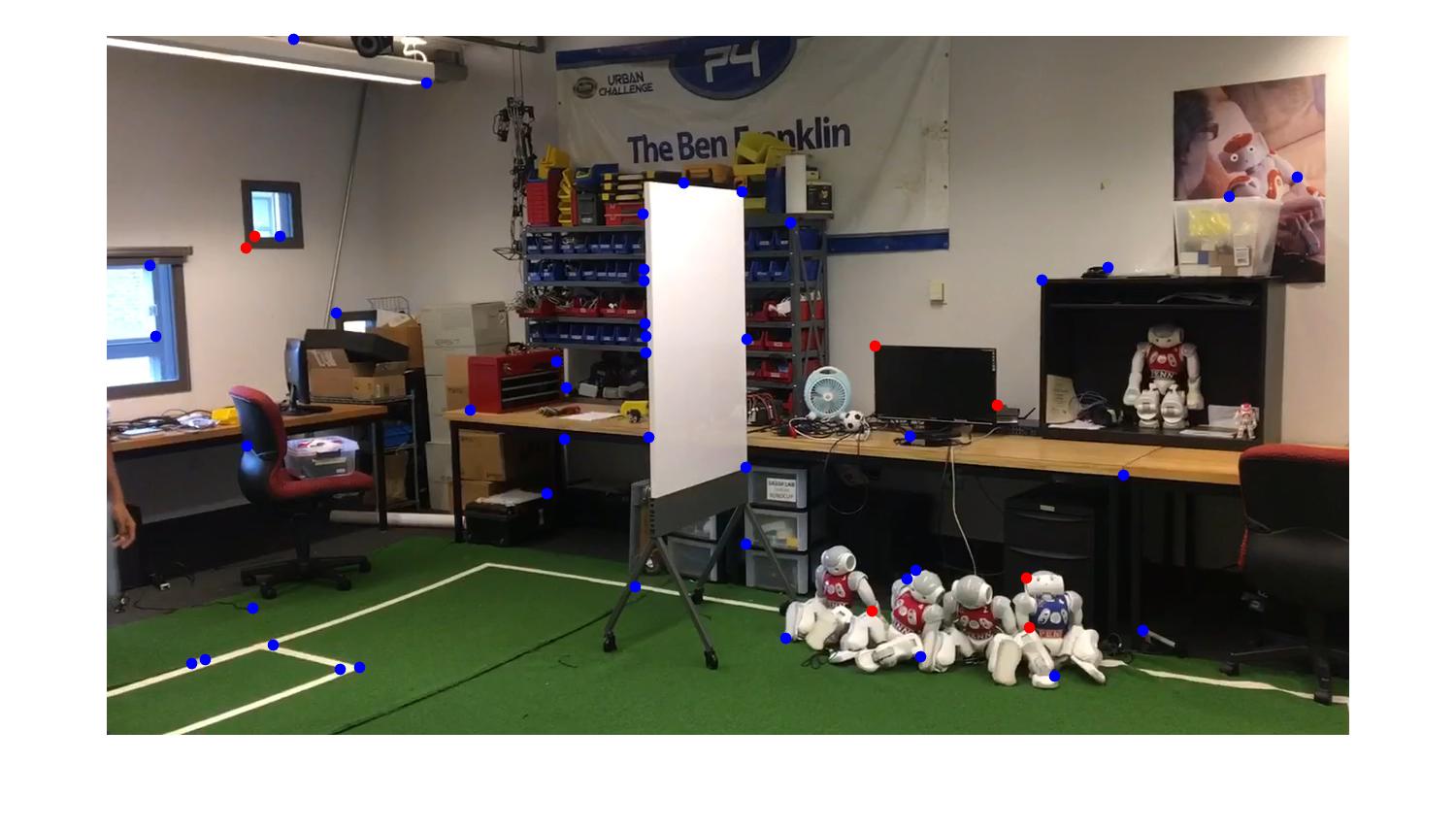
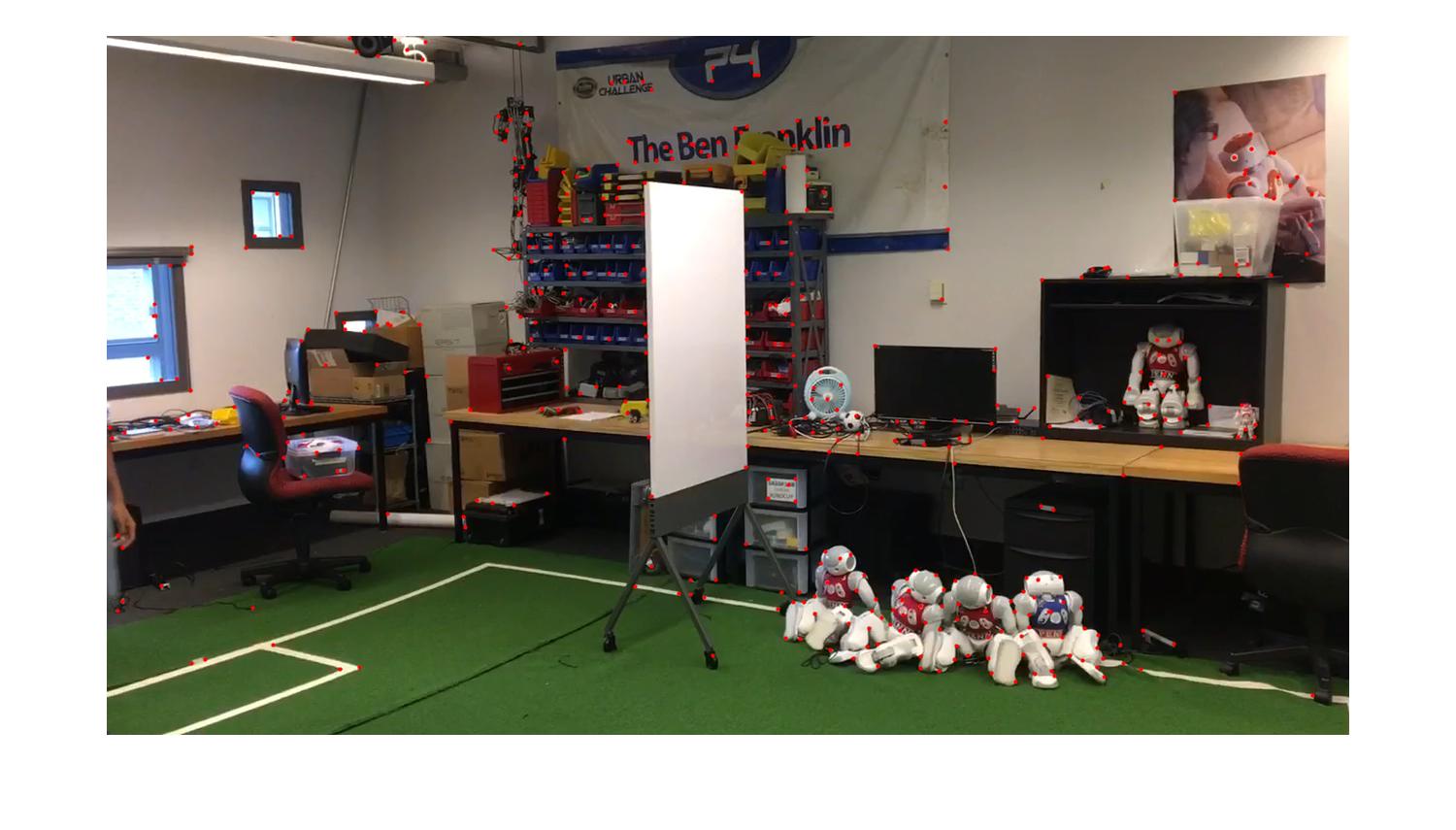
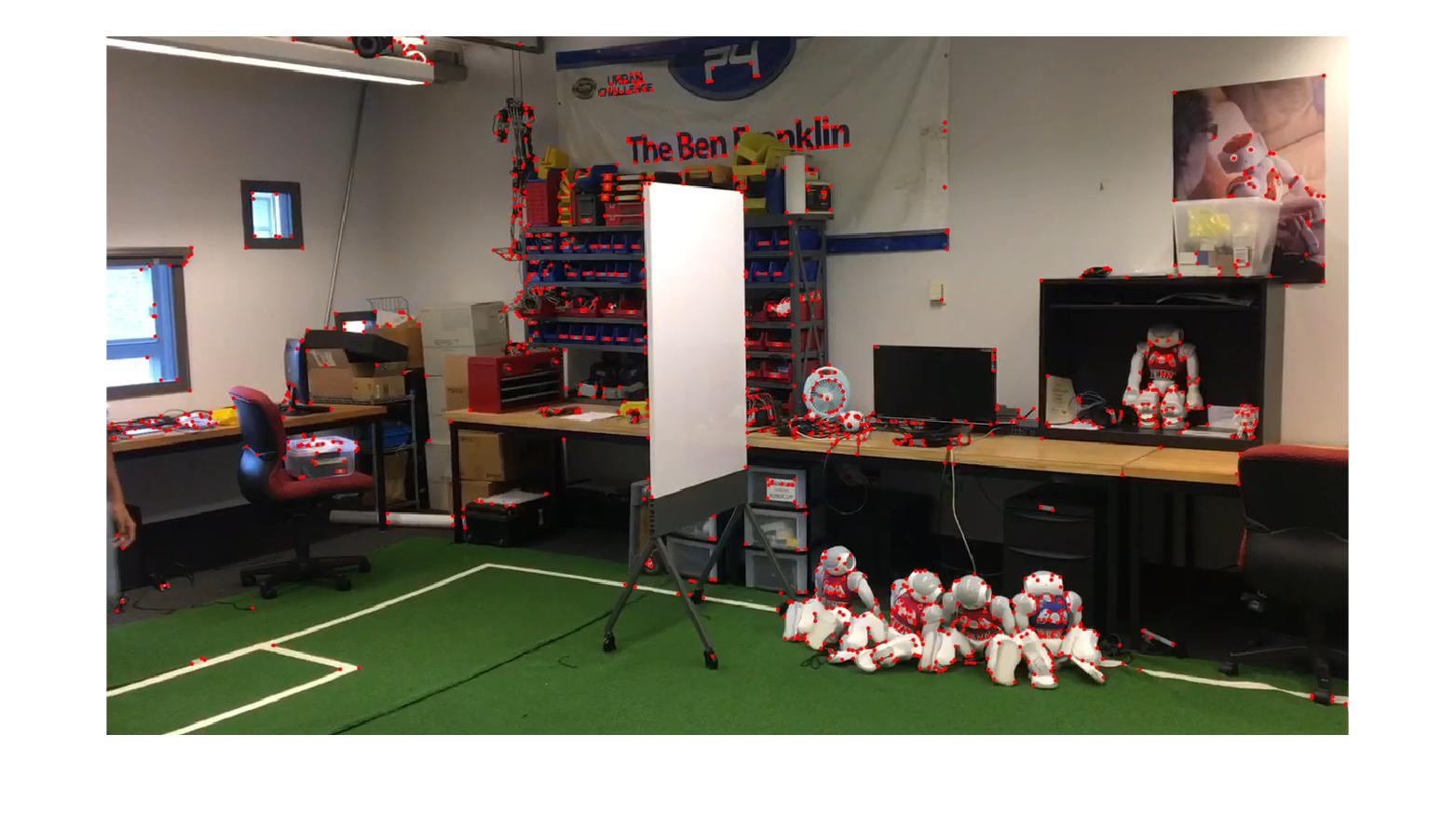
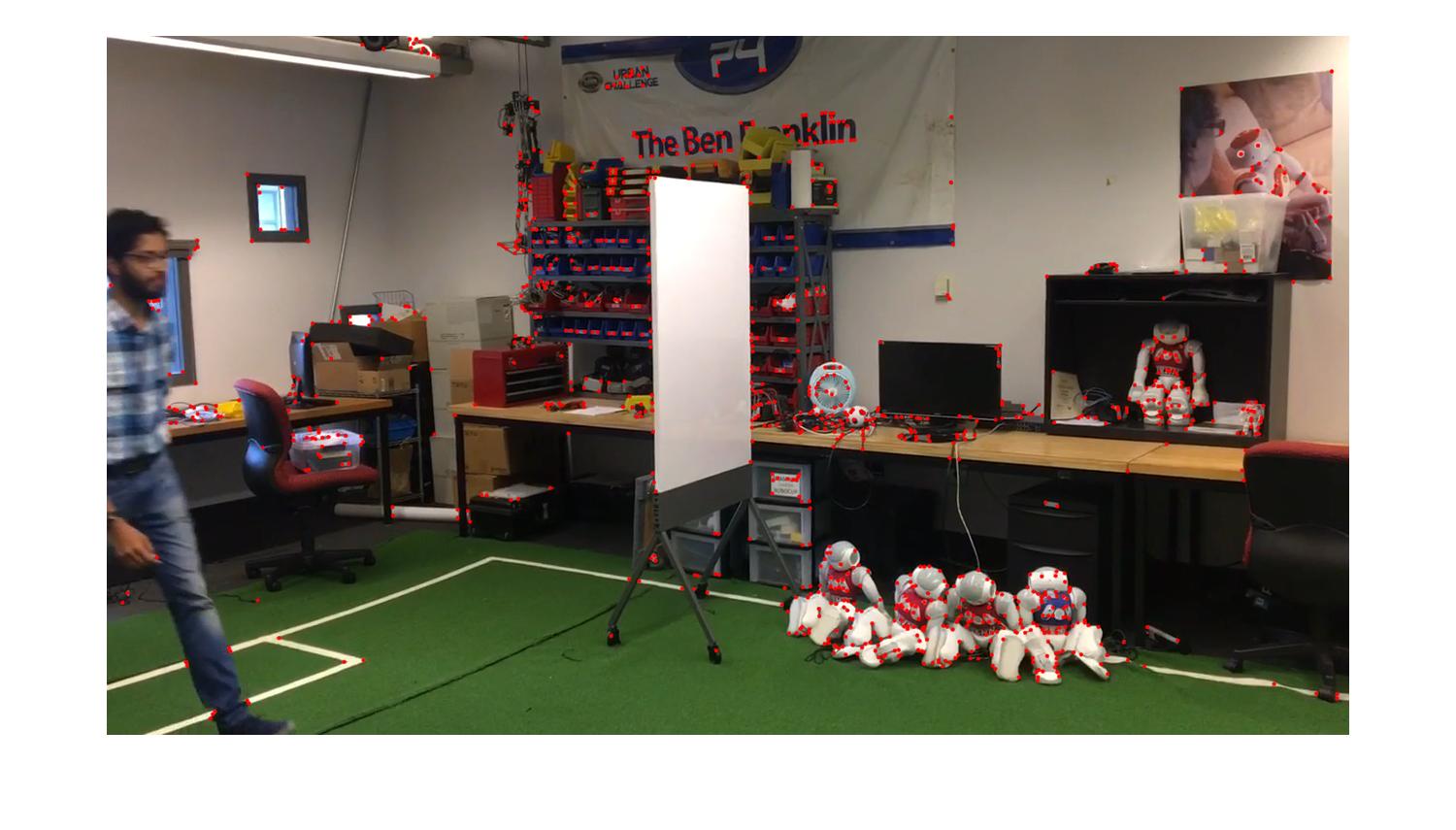
Original corner points that are detected by Harris features



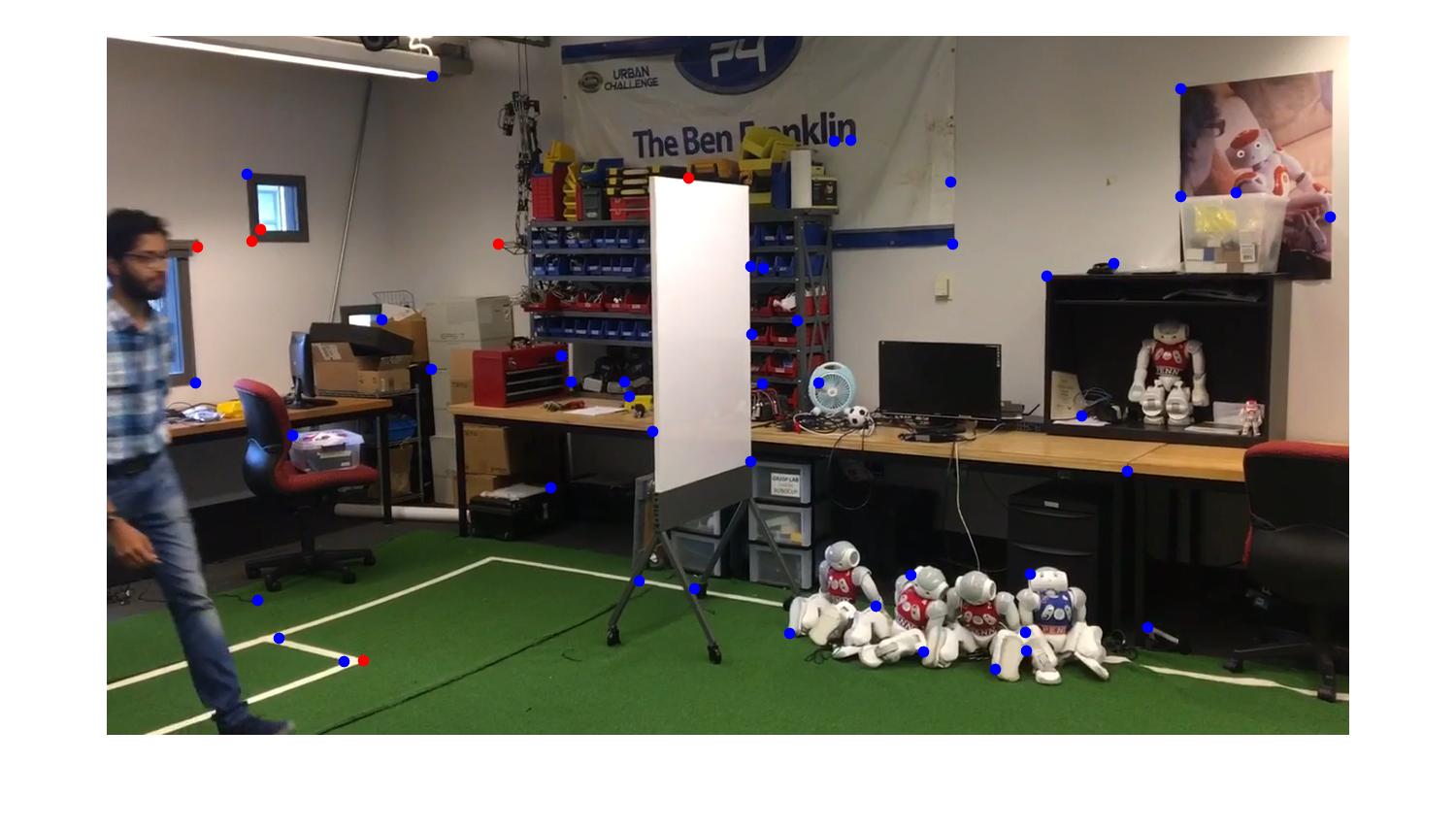
After ANMS these are the points that are left

Post RANSAC, outliers are shown in blue dots and inliers are shown in red dots. We had 6 inliers out of a total matched 48 points.

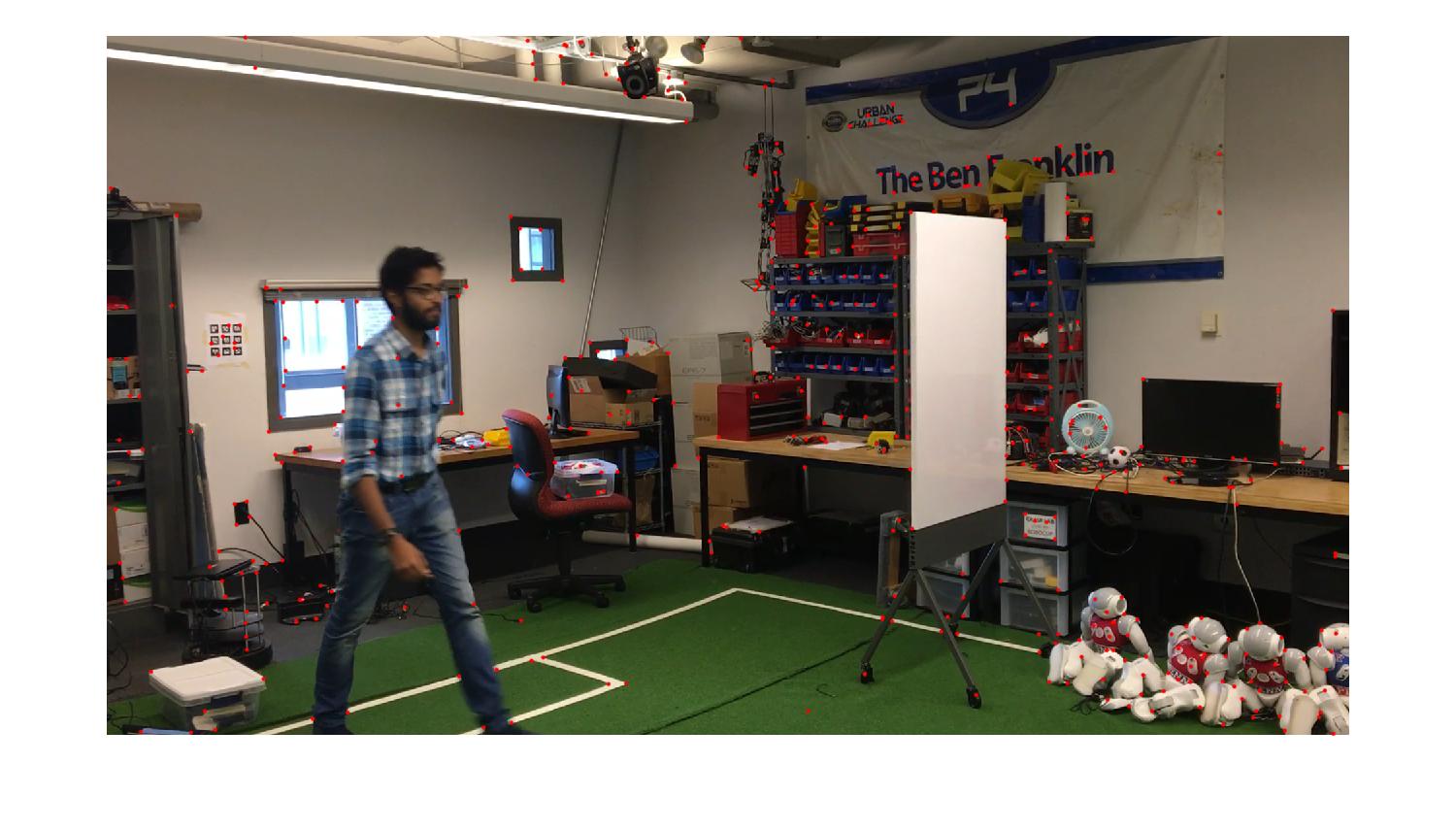


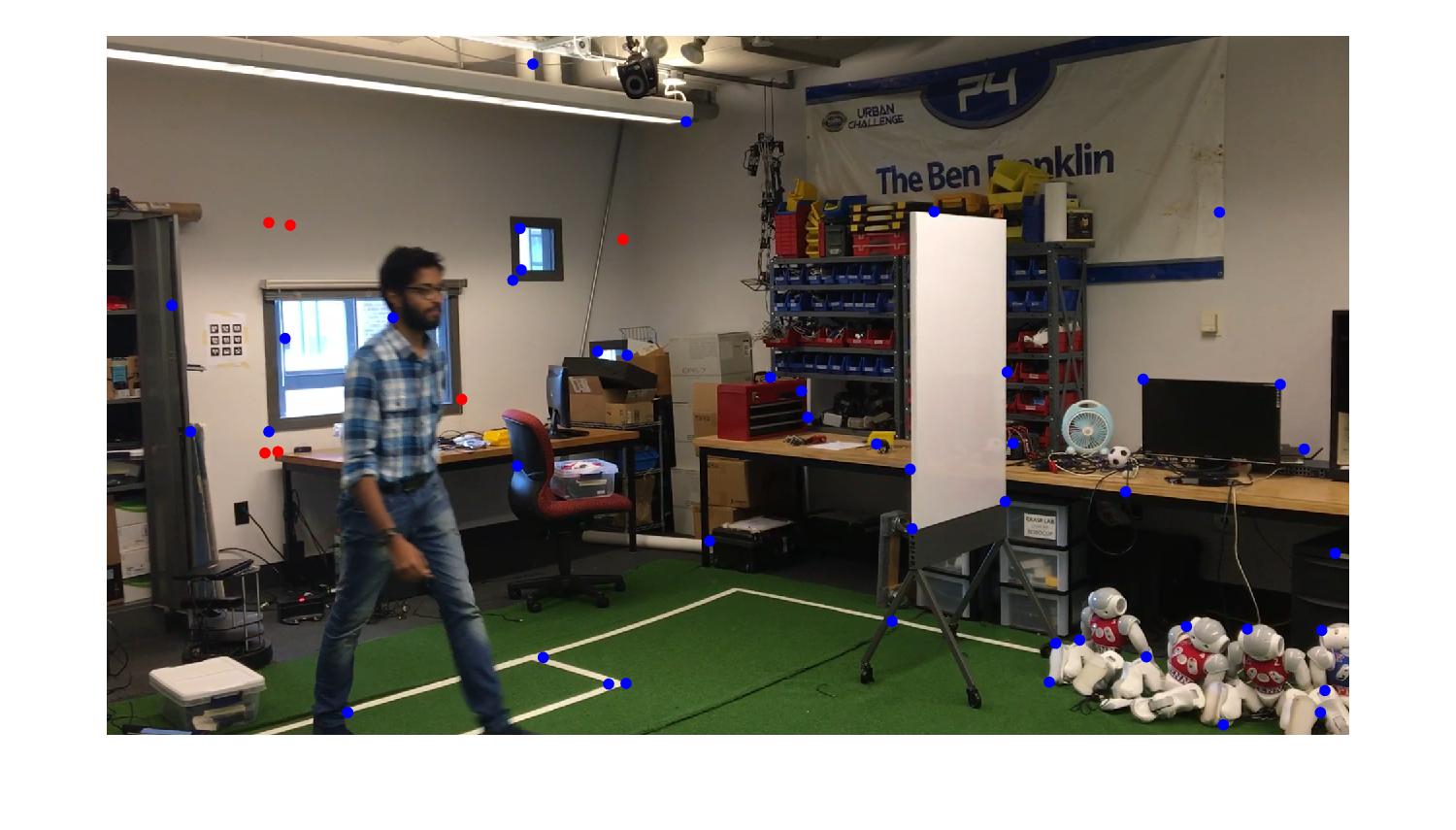


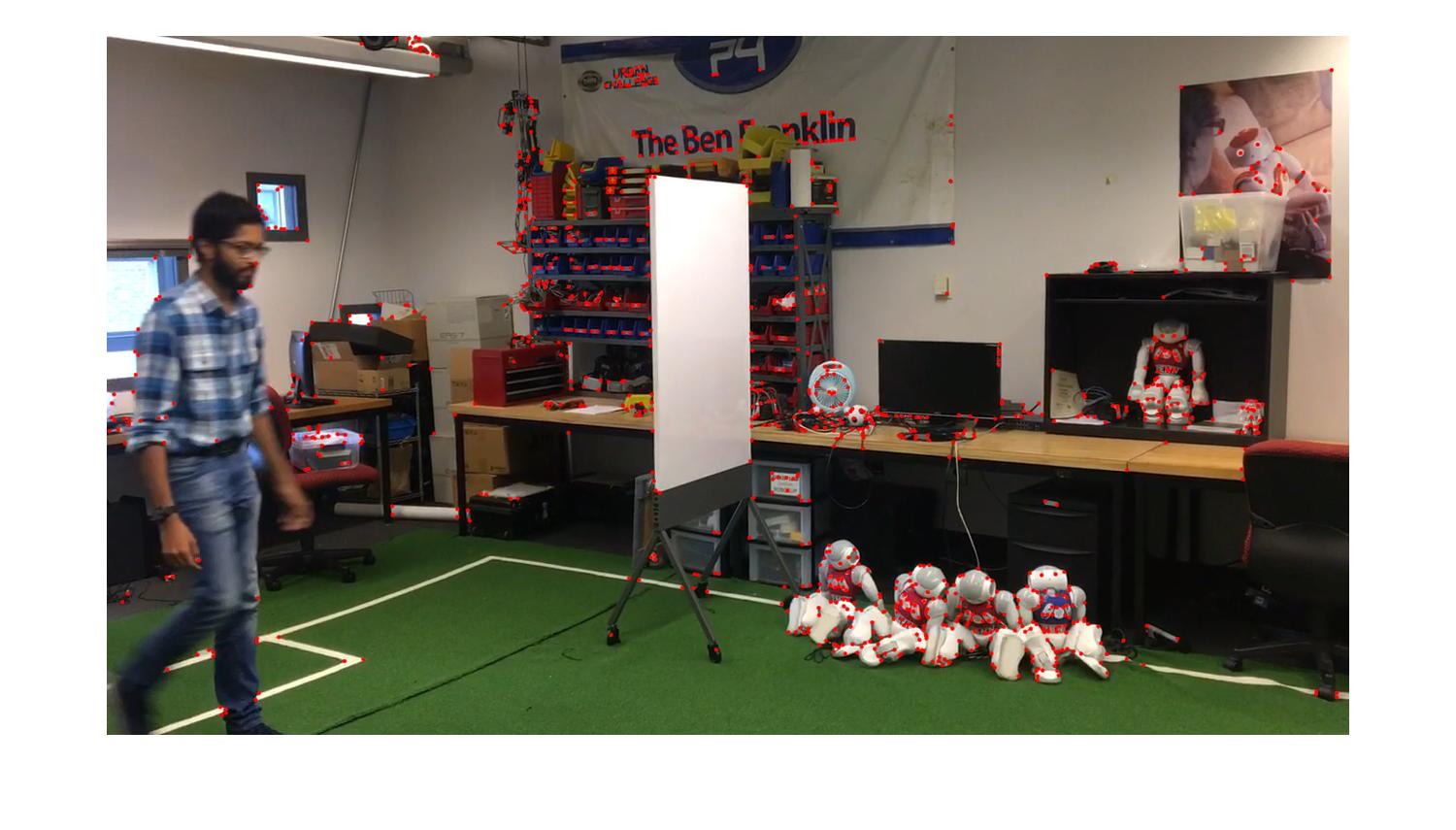


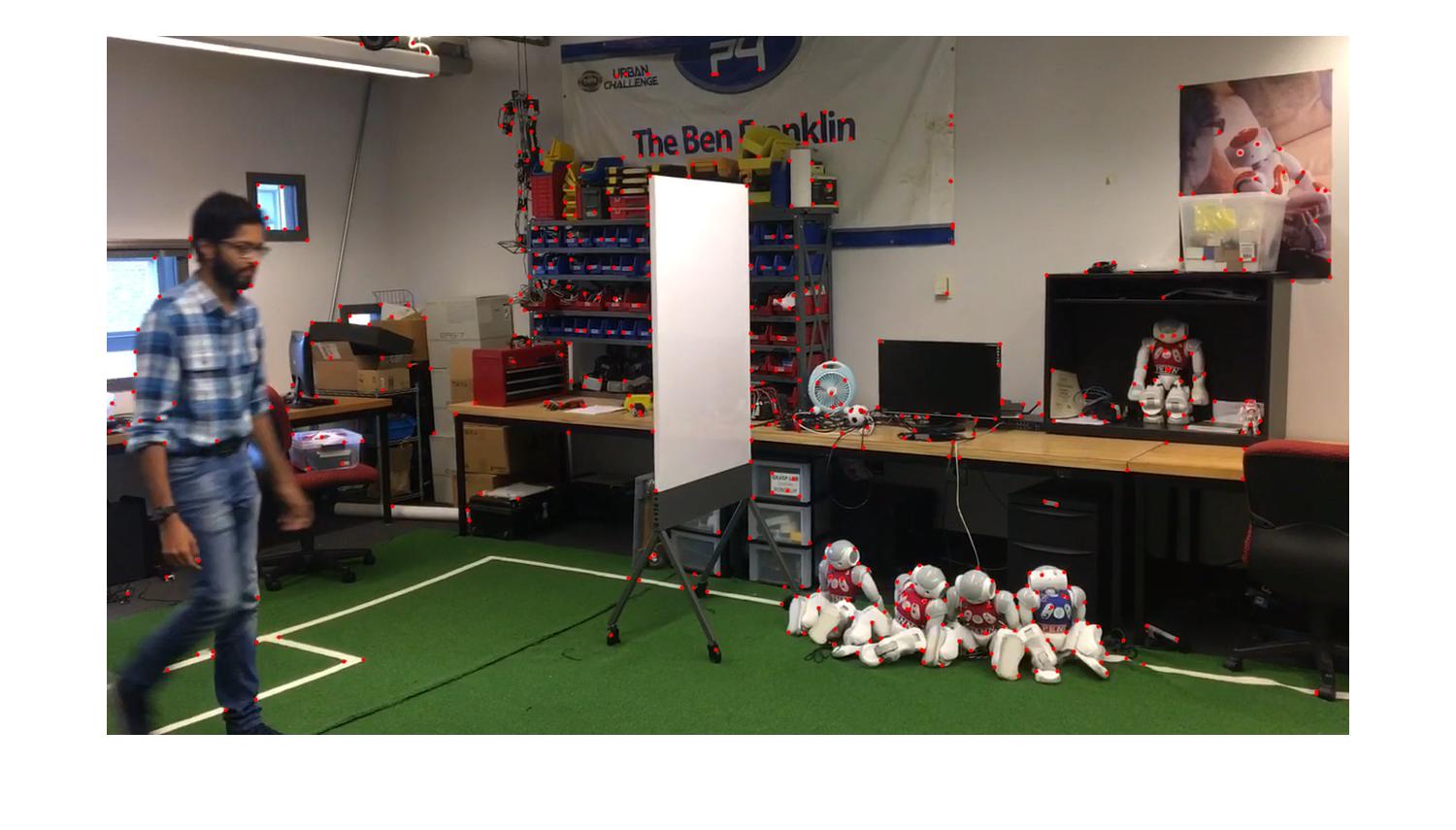


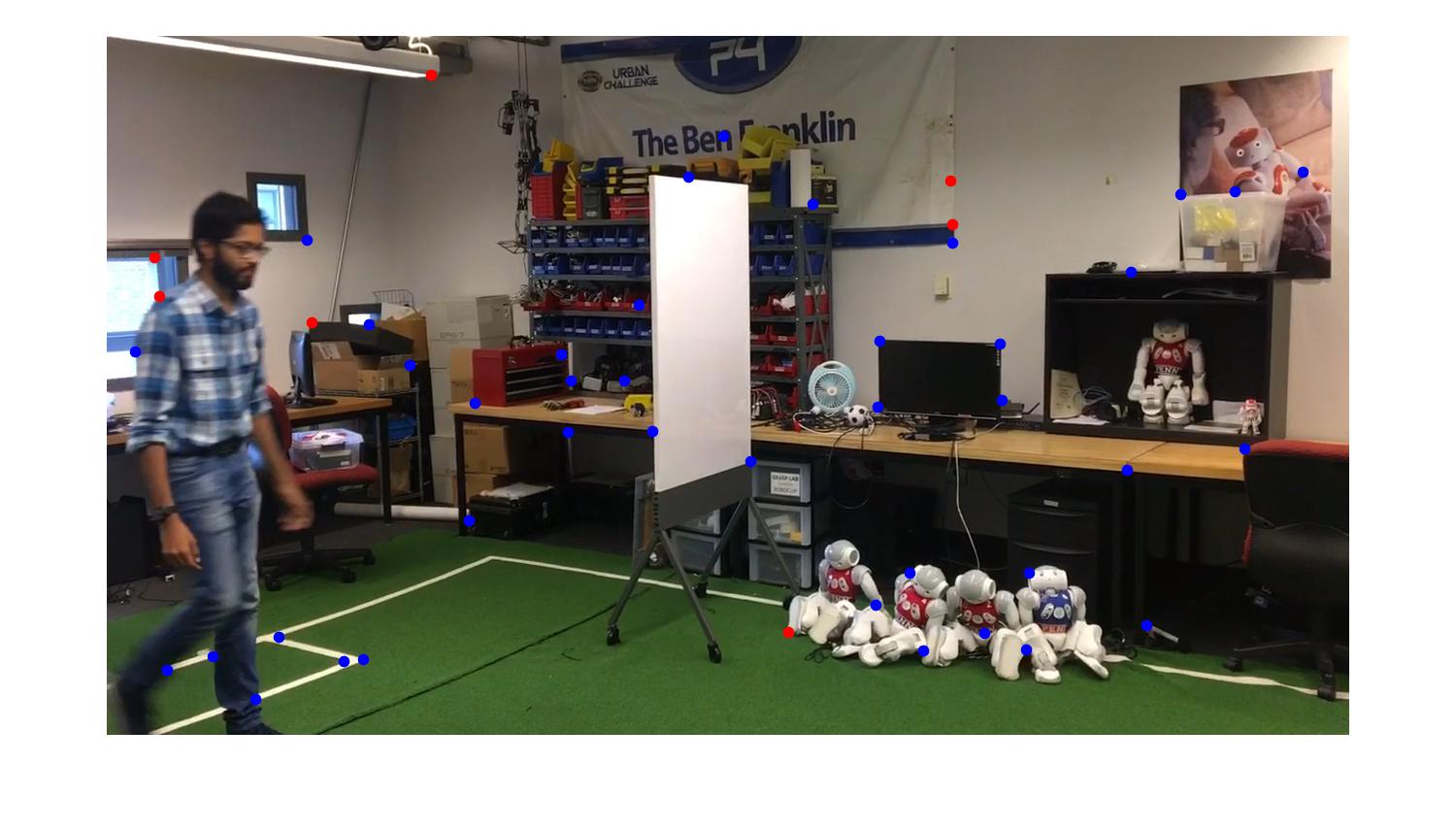












No additional features of implementation

References to 3rd party code:

We only used provided Matlab functions for this assignment. These include functions like DetectCornerHarris and DNNsearch, plus the provided homography functions by the TAs.